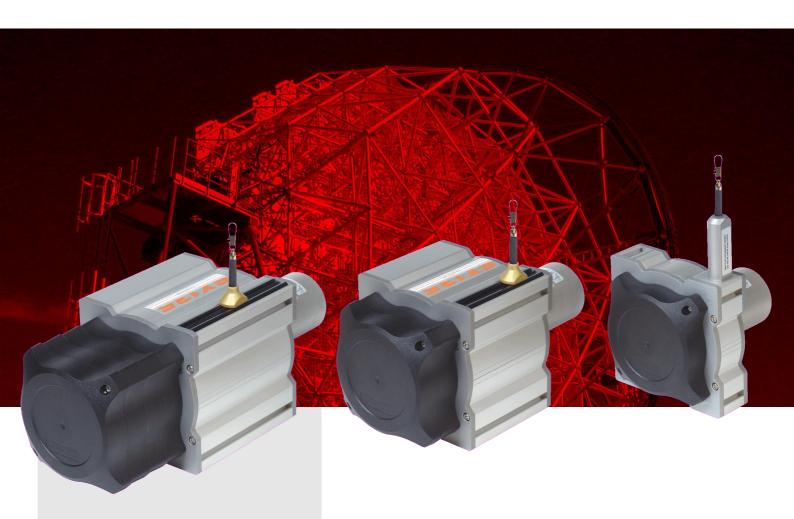
# DRAWWIRE SENSOR



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## SX135 Long Range

### **Key-Features:**

- Ranges 8000...42.500 mm
- Analog Digital Incremental Digital Absolute
- Linearity up to ±0.02 % of FS
- Protection class up to IP67
- High dynamics
- High EMC-grade
- Customised versions available

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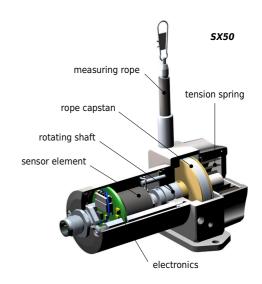


## INTRODUCTION

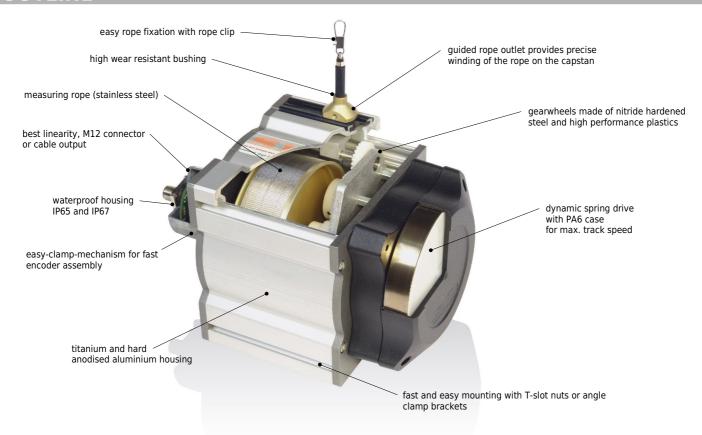
WayCon Positionsmesstechnik GmbH is a manufacturer of high quality draw wire position transducers for industrial use. Due to its small overall size, its short assembly time and its possible customisation, the SX sensor technology is a cost-effective and flexible solution for a wide range of industrial applications. The dynamics of the draw wire transducer allows a high motion speed and acceleration of the measuring target. Its rugged design and high quality makes applications in harsh industrial environments possible. Special instruments are available with mounting service of encoder on site, as well as customised versions of housing.

#### Sensor principle:

A constant spring force coils the measuring rope accurately, single-layered on an ultralight rope capstan, so that its linear motion is converted into rotation. The sensor element (encoder) provides the output signal required.



## OUTLINE



## **APPLICATIONS**

- lifting tables and platforms
- positioning of fork-lifts
- · level control system
- portal frames and gantry cranes
- lifting and rescue technology

- · hydraulic cylinder
- property management
- linear guides
- x-y-axis positioning
- · pipe displacement

### **OPTIONS**

#### SSB8 / SSB10 / IP67 / CO / ICP / TEMP-40

SSB8 (up to range 8 m) / SSB10 (range 10-42.5 m): All ball bearings are made of stainless steel. This option is suitable for applications in humid or moderate corresive environmental conditions

IP67: Use option IP67, if sensor is fully immersed in water (temporarily). Like option SSB8, only stainless steel ball bearings are mounted. Note that with this option there may occur a light hysteresis in the output signal due to the special sealing. The max. acceleration is reduced to 60 % of the specified value.

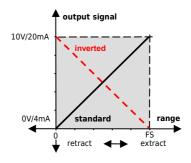
CO: By the use of a special technology all components of the housing and the inner mechanics become HARTCOAT® coated. This coating is a hartanodic oxidation that protects the sensor from corrosion by aggressive media (e. g. sea water) with a hard ceramics-like layer. This option includes SSB8.

ICP: This version combines the options CO (HARTCOAT®-coating) and IP67 (protection class IP67). In addition, a increased corrosive protection is achieved by the use of special components.

TEMP-40: The use of special components enhances the operating temperature to -40...+85 °C.

#### IN

The analog signal of the sensor is increasing by extracting the rope (standard). Option IN inverts the signal, i. e. the signal of the sensor declines by extracting the rope.



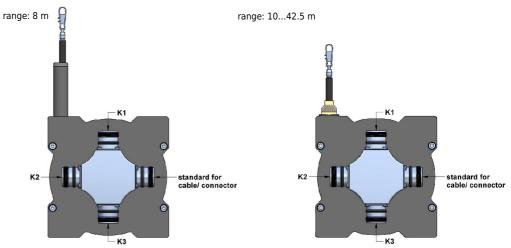
#### L05 / L02

Improved linearity on 0.05% of measuring range. Resolution, repeatability and sensibility remain unchanged.

Improved linearity on 0.02% of measuring range. Resolution, repeatability and sensibility remain unchanged. This option is only available for incremental sensors.

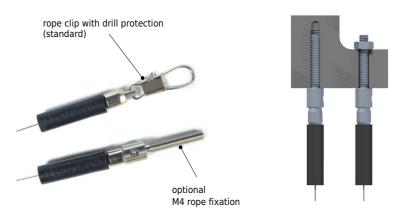
#### K1 / K2 / K3

Optional cable/ connector orientation for sensors with digital output/ encoder.



#### M4 rope fixation

Optional, pivoted rope fixation with screw thread M4, length 22 mm. Ideal for attachment to through holes or thread holes M4.





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## SERIES SX135





邹工: 17316386953

output	analog o	utput				digital ou	tput incre	mental		
	potentiometer/ 010 V/ 420 mA (page 10)					A/B-pulse, 90° phase-delayed (page 11)				
sensor element	hybrid pote	entiometer				incrementa	al encoder/ o	optical code	disc	
connection	M12-conne	ector or cabl	e output 2 n	n		connector	or cable out	put 2 m		
protection class	IP65, optio	nal IP67				IP65, optio	nal IP67			
humidity	max. 90 %	relative, n	o condensat	ion		max. 90 %	relative, no	o condensati	on	
temperature	-20+85	°C				-20+85	°C			
weight	approx. 42	200 g				approx. 42	.00 g			
housing	aluminium	, titanium-g	rey anodised	d, spring case	e PA6	aluminium	, titanium-gı	rey anodised	l, spring case	e PA6
Technical data - analog output										
ranges [m] *	8	10	12	15	20	25	30	35	40	42.5
linearity [%]	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1	0.1
linearity optional [%]	0.05	0.05	0.05	0.05	0.05	0.05	0.05	0.05	0.05	0.05
Technical data - digital output incremental										
ranges [mm] *	8	10	12	15	20	25	30	35	40	42,5
linearity [%]	0.05, inde	pendent of r	measuremer	nt range						
linearity optional [%]	0.02, inde	pendent of i	measuremer	nt range						
available resolution, range 8 m [pulses/ mm]	0.28	0.28 1.4 2.8 5.6		5.6	14					
available resolution, range 10 - 42.5 m [pulses/ mm]	0.3	1.5	3	6	15					
Z-pulse-distance, range 8 m [mm]	357.14									

Z-pulse-distance, range 10 - 42.5 m [mm] \* other measurement ranges on request

Mechanical data				
	rope t	ension	velocity	acceleration*
range [m]	F <sub>min</sub> [N]	F <sub>max</sub> [N]	V <sub>max</sub> [m/s]	a <sub>max</sub> [m/s²]
8	7.2	10.4	10.0	140
10 / 12	4.8	7.2	6.0	80
15	6.8	11.2	6.0	80
20	6.4	9.2	5.0	60
25	7.8	11.4	5.0	60
30	6.4	9.6	5.0	60
35	7.4	11.6	5.0	60
40 / 42.5	5.4	9.0	5.0	60

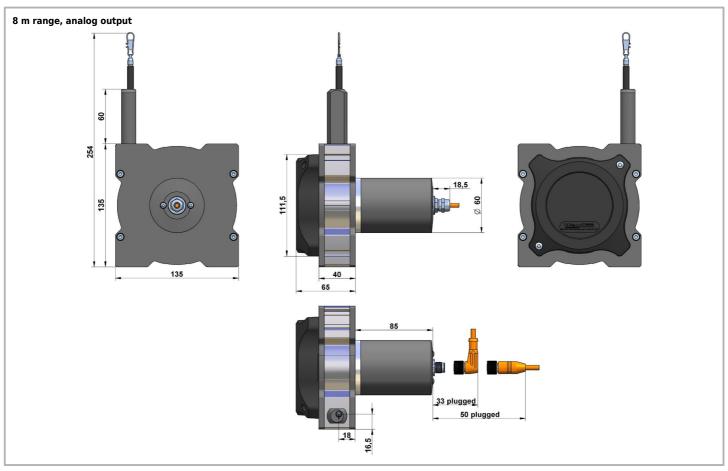
333.33

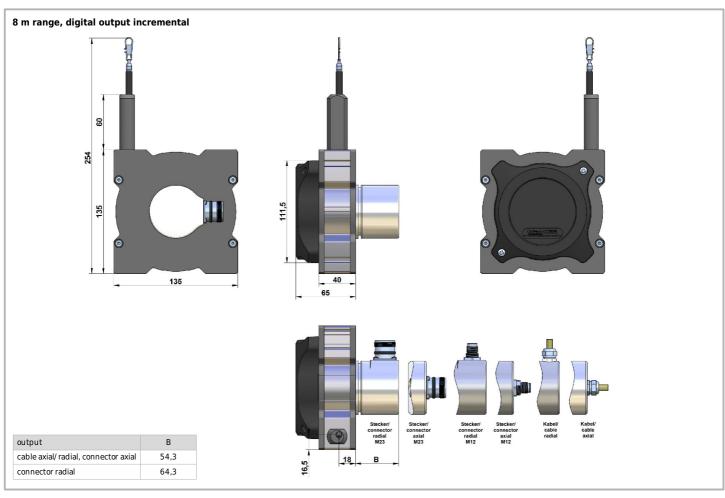


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<sup>\*</sup> reduced to 60 % with option IP67

## TECHNICAL DRAWING



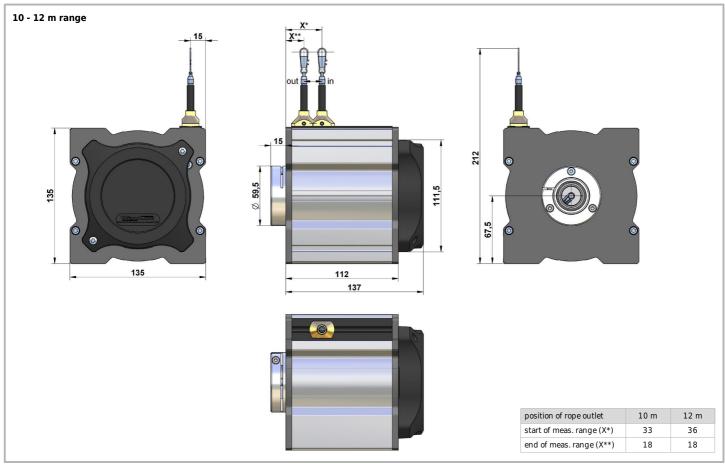


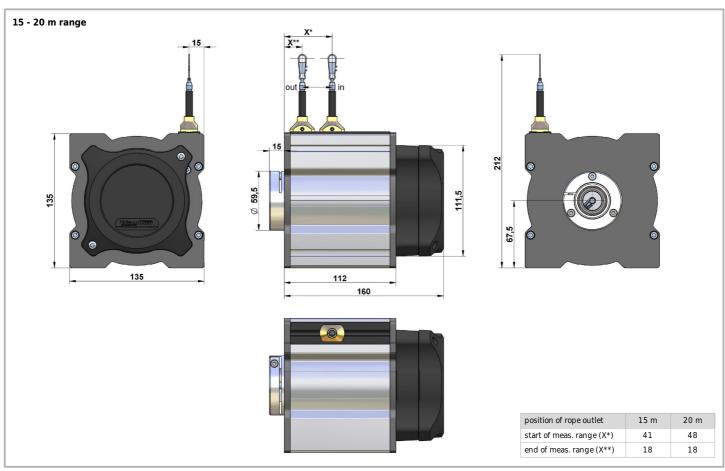
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## TECHNICAL DRAWING

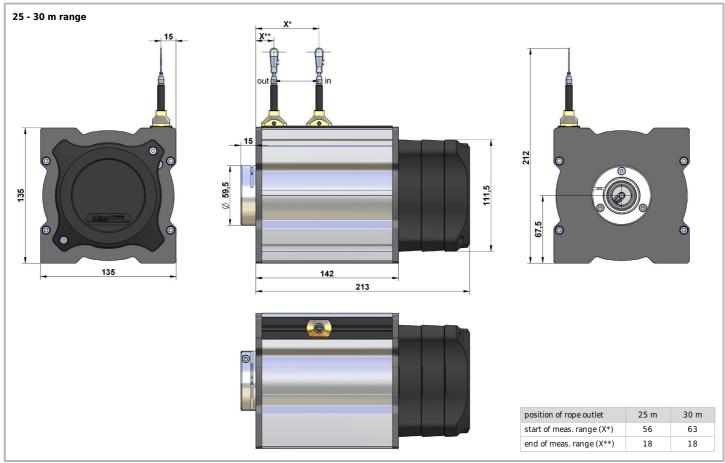


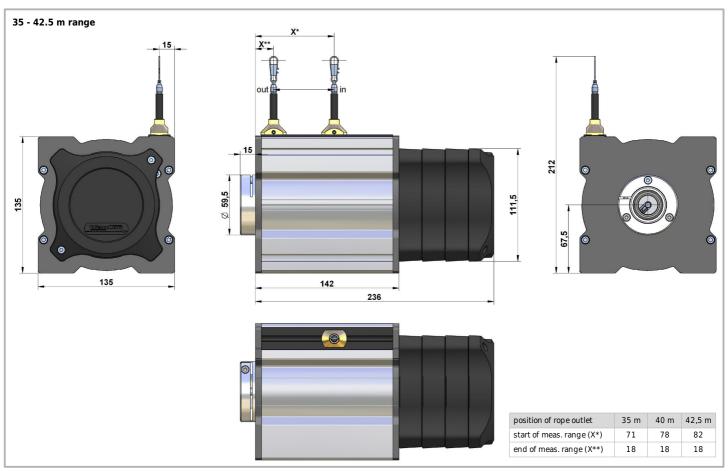


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## TECHNICAL DRAWING

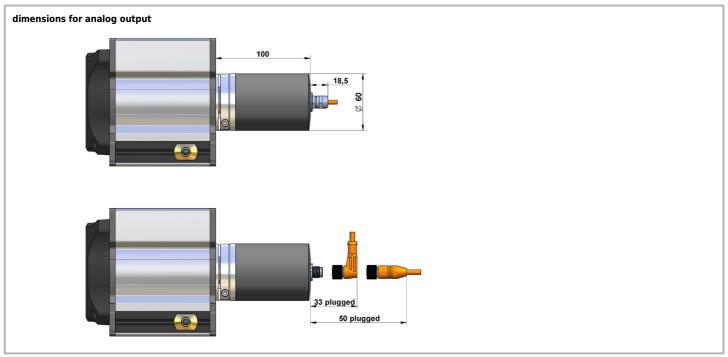


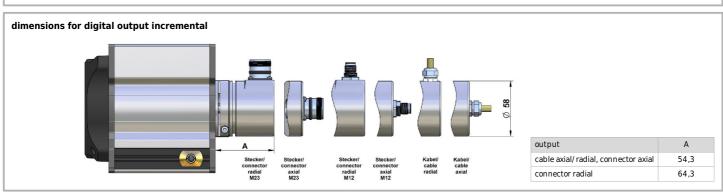


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## TECHNICAL DRAWING





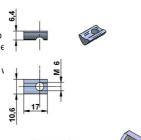
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## **MOUNTING OPTIONS**

#### 1. by using the grooves in the sensor housing

The included T-slot nuts can be easily inserted into grooves of the sensor housing. The nuts have a methread M6.

Each sensor up to 20 m measurement range comes  $\nu$  2 nuts, from 20 to 42.5 m for nuts are included.

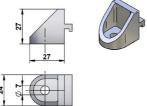


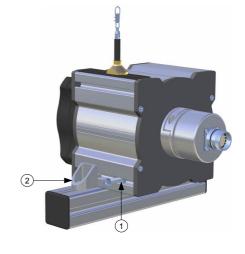


#### 2. by angle clamp brackets

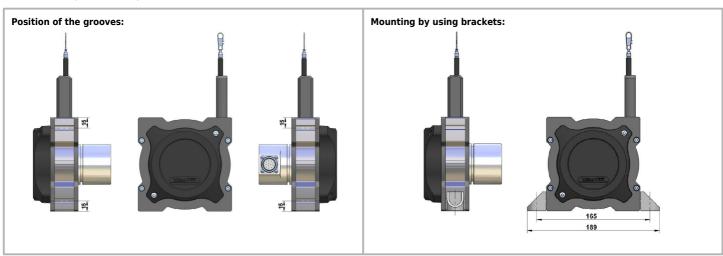
The angle clamp brackets feature a bore for M6 scre to fix it on a plate/ slab or a profile.

Each sensor up to 20 m measurement range comes w 2 brackets, from 20 to 42.5 m for brackets are include





**Important:** The grooves of the sensor housing, the nuts and brackets are compatible to the aluminium building kit system from *item Industrietechnik GmbH* (www.item.info).

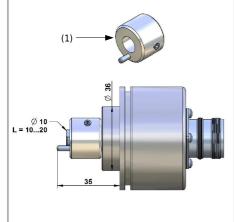


### ENCODER ASSEMBLY BY EASY-CLAMP-MECHANISM

IMPORTANT: All incremental and absolute encoders must have a clamping flange (diameter 36 mm), a shaft diameter of 10 mm and a shaft length of 10-20 mm.

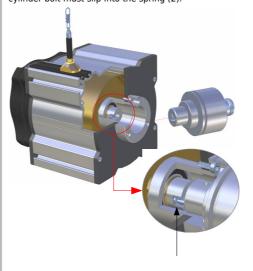


Please mount the included coupling (1) on the shaft of the encoder and fix the set screw. Therefore you will need a hexagon screwdriver, size 2. Be careful that the dimension between contact surface of the encoder and the end of the cylinder bolt is 35 mm.



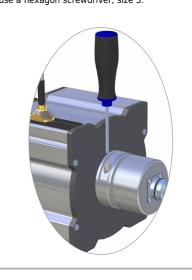
2.

Please mount the encoder into the easy-clamp-flange. The cylinder bolt must slip into the spring (2).



3.

By tightening the radial screw the encoder will be clamped and secured from twisting. Please use a hexagon screwdriver, size 3.

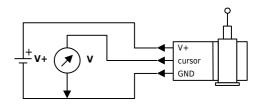


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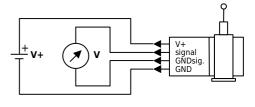
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## ANALOG OUTPUT

Potentiometer (voltage divider)	
output	1 kOhm
supply voltage	max. 30 V
recommended cursor current	< 1 µA
noise	depending on supply
working temperature	-20+85 °C
temperature coefficient	± 0.0025 %/K

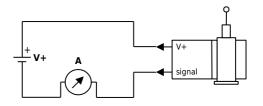


010 V voltage output	
output	010 V, galvanically isolated, 4 conductors
supply voltage	1230 VDC
max. current consumption	22.5 mA (unloaded)
output current	max. 10 mA, min. load 10 kOhm
dynamics	< 3 ms from 0100 % and 1000 %
noise	3 mV <sub>pp</sub> typically, max. 37 mV <sub>pp</sub>
inverse-polarity protection	yes, infinite
short-circuit proof	yes, permanent
working temperature	-20+85 °C
temperature coefficient	0.0037 %/K
electromagnetic compatibility (EMC)	according to EN 61326-1:2006



note: GNDsignal and GND may be connected in 3-wire system.

420 mA current output	
output	420 mA, 2 conductors
voltage supply	1230 VDC
output current	max. 50 mA in case of error
dynamics	< 1 ms from 0100 % and 1000 %
noise	0.03 mA $_{pp}$ = 6 mV $_{pp}$ at 200 Ohm
inverse-polarity protection	yes, infinite
working temperature	-20+85 °C
temperature coefficient	0.0079 %/K
electromagnetic compatibility (EMC)	according to EN 61326-1:2006



## CONNECTION

#### cable output:

axial 2.0 meter standard, other cable lengths optional

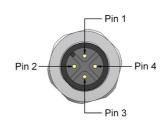
type: TPE, flexible diameter: Ø 4.5 mm stranded wire: 0.25 mm²

temperature range: fixed installation -30...+85 °C, flexible installation -20...+85 °C

pin	wire colour	10 V	420 mA	1 kOhm
1	brown	V +	V +	V +
2	white	signal	n. c.	cursor
3	blue	GND	signal	GND
4	black	GND signal	n. c.	n. c.

#### 4-pin M12 connector output (socket):

profile/ view on solder side of mating connector

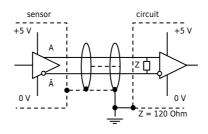


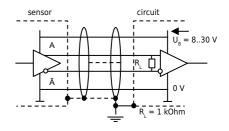
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## DIGITAL OUTPUT INCREMENTAL

Electrical data	Linedriver L	Push Pull G
	RS422 (TTL-compatible)	
supply voltage	5 VDC, ±5 %	830 VDC
current consumption (no load)	typical 70 mA, max. 100 mA	typical 80 mA, max. 150 mA
max. load/ channel	±20 mA	± 30 mA
max. pulse frequency	300 kHz	300 kHz
min. signal level high	2.5 V	U <sub>B</sub> - 3 V
max. signal level low	0.5 V	2.5 V
recommended circuit		



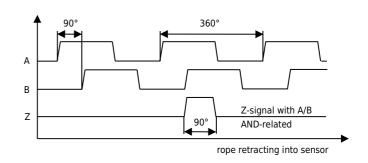


connection	connector 12-pin (counterclockwise), cable output 2 m	connector 12-pin (counterclockwise), cable output 2 m
protection class	IP65, optional IP67	IP65, optional IP67
max. cable length	up to 1000 m	up to 250 m

#### output signal

Pulses A and B are  $90^{\circ}$  phase-delayed (detection of direction). The Z-signal recurs with pulse distance Z and may be used as point of reference.

Diagram shows the signal without inverted signals; time-line for return of rope.



## CONNECTION

Assignment											
signal	0 V	$U_{_{B}}\!+\!$	0 V <sub>sens</sub> *	$U_{Bsens}\!+*$	Α	A -	В	В -	Z	Z -	screen
12-pin connector	10	12	11	2	5	6	8	1	3	4	housing
8-pin connector	1	2	-	-	3	4	5	6	7	8	housing
wire colours	white	brown	black	violet	green	yellow	grey	pink	blue	red	housing

\* For Linedriver L only. For long cable lengths it may occur that the operating voltage at the sensor does not suffice due to the output resistance. With the sensor lines  $0V_{gens}$  and  $+UB_{gens}$  the operating voltage can be checked and, if necessary, be readjusted at the input connection.

# **12-pin connector output (socket)**Profile/ view on solder side of mating connector



**8-pin connector output (socket)**Profile/ view on solder side of mating connector



#### cable output

radial/ axial 2 metre standard other cable length optional

type: UL2464/ 1061, LiYY, flexible

outer diameter: ø 6,5 mm stranded wire: 10 x 0,25 mm²

temperature range: fixed installation -30...+80 °C,

flexible installation -20...+80 °C

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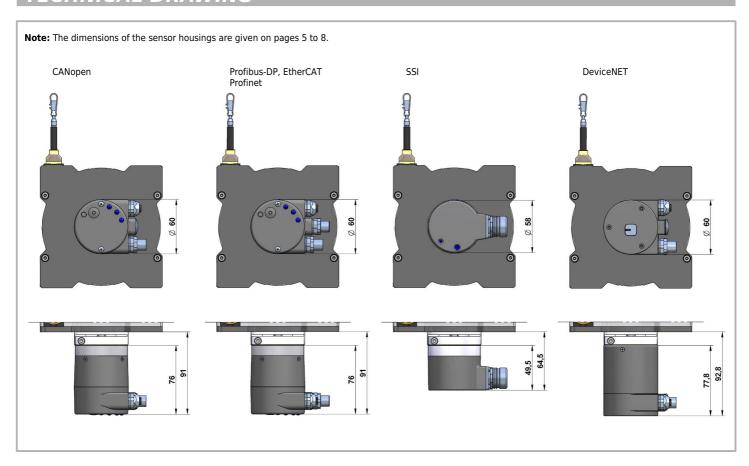
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## DIGITAL OUTPUT ABSOLUTE

output	Profibus-DP	CANopen	DeviceNet	EtherCAT	SSI	Profinet
scalable resolution	yes	yes	yes	yes	no	yes
standard resolution at range 8 m [pulses/ mm]	22.94	22.94	22.94	22.94	22.94	22.94
max. resolution at range 8 m [pulses/ mm]	183.50	183.50	22.94	183.50	-	183.5
standard resolution at range 10 - 42.5 m [pulses/ mm]	24.58	24.58	22.94	24.58	24.58	24,58
max. resolution at range 10 - 42.5 m [pulses/ mm]	196.61	196.61	22.94	196.61	-	196.61
supply voltage	1030 VDC	1030 VDC	1030 VDC	1030 VDC	1030 VDC	1030 VDC
current consumption (no load, at 24 VDC)	90 mA	65 mA	max. 290	90 mA	25 mA	200 mA
protection class	IP65	IP65	IP65	IP65	IP65	IP65
protection class optional	IP67	IP67	-	IP67	IP67	IP67
working temperature	-20+80 °C	-20+80 °C	-20+80 °C	-20+80 °C	-20+80 °C	-20+80 °C

Other encoder types (supply voltage, resolution, cable/ connector output) are available on request.

## TECHNICAL DRAWING



## CONNECTION

encoder type	
Profibus-DP	bus terminal cover, 3 x M12-connector (2 x male, 1 x female)
CANopen	removable bus terminal cover, 2 x M12-connector (1 x male, 1 x female)
DeviceNET	bus terminal cover, 2 x M12-connector (1 x male, 1 x female)
EtherCAT, Profinet	bus terminal cover, 3 x M12-connector (1 x male, 2 x female)
SSI	12-pin M23-connector (pins counter clockwise). mating connector CON012-5

For further information and electrical connection please see Sendix Absolute Encoder data sheet



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### **ACCESSORIES**

Cable with mating connector M12, shielded K4P: 4-pole for analog output: Poti/ 10V/ 420A K8P: 8-pole for digital output incremental

 cable with straight connector:
 cable with angular connector:

 K4P2M-S-M12 / K8P2M-S-M12
 2 m
 K4P2M-SW-M12 / K8P2M-SW-M12
 2 m

 K4P5M-S-M12 / K8P5M-S-M12
 5 m
 K4P5M-SW-M12 / K8P5M-SW-M12
 5 m

 K4P10M-S-M12 / K8P10M-S-M12
 10 m
 K4P10M-SW-M12 / K8P10M-SW-M12
 10 m



Mating connector M12, shielded, for self assembly D4: 4-pole for analog output: Poti/ 10V/ 420A D8: 8-pole for digital output incremental

straight connector: D4-G-M12-S / D8-G-M12-S angular connector: D4-W-M12-S / D8-W-M12-S



## Cable with mating connector M23, for digital output incremental and SSI, shielded

Incremental: SSI:

 K8P2M-S-M23
 2 m
 K12P02M-S-M23-SSI
 2 m

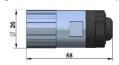
 K8P5M-S-M23
 5 m
 K12P05M-S-M23-SSI
 5 m

 K8P10M-S-M23
 10 m
 K12P10M-S-M23-SSI
 10 m

K12P15M-S-M23-SSI 15 m

## Mating connector CON012-S for digital output incremental and SSI, shielded

M23, straight, female connector, 12-pin, metal housing





### Cable with mating connector M12 for digital output CANopen and Profibus, shielded

CANopen: Profibus:

K5P2M-B-M12-CAN 2 m, female connector K5P2M-B-M12-PROF 2 m, female connector K5P2M-S-M12-CAN 2 m, male connector K5P2M-S-M12-PROF 2 m, male connector K5P2M-SB-M12-PROF 2 m, female - male M12-PROF-AW terminating resistor



#### Deflection pulley - UR2

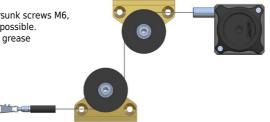
By using the deflection pulley, the rope can be looped around to e. g. measure in places that are difficult to access or to protect the sensor from inclined traction on the rope. Several pulleys may be used.

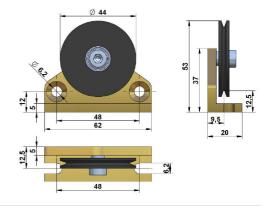
material: anodised aluminium, POM mounting: by 2 hexagon socket or countersunk screws M6,

vertical or horizontal mounting possible. Ball bearings with special low temperature grease

and RS-sealing.

Temperature range: -40...+80 °C.





#### Rope extension - SV

For bridging a greater distance from the measuring target to the sensor a rope extension can be applied. The rope clip must not be guided over the deflection pulley.

Please specify the length needed in your order. The minimum length is 150 mm.

SV1-XXXX: rope extension (150...4995 mm) SV2-XXXX: rope extension (5000...19.995 mm) SV3-XXXX: rope extension (20.000...40.000 mm)

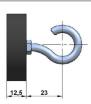


#### Magnetic clamp - MGG1

Use the magnetic clamp to quickly attach the rope to metallic objects without any assembly time. A rubber coating provides gentle contact (e. g. on varnished surfaces) and prevents from slipping due to vibration.

The magnet consists of a neodym core for an increased adhesive force of 260 N. The hook makes it easy to attach the rope clip (drill protection).





Other cable length are available on request.

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### **ACCESSORIES**

#### Digital distance and speed measurement - PAX

Use PAX display to visualise the covered distance or the speed (tachometer sensor) of the position transducer. It enables a transmission of the measurement data to the computer via interface. The comparator allows a good-bad-evaluation (limit values function).

inputs: incremental/ analog, 2 independent counter, 1 tachometer sensor

analogue output: 0...20 mA, 4...20 mA, 0...10 V (plug in card)

RS485, RS232, DeviceNet, USB, Profibus (plug in cards) serial interfaces:

Protection class (front panel): IP65 6 digits display:

11...36 VDC or 85...250 VAC power supply:

For further information please see the data sheets of the PAX display series.



### NSTALLATION

- Mount the sensor at the designated place by using the fixing holes before extracting the rope and before attaching the rope to the measuring target.
- Open the rope clip (not with set screw M4) after the sensor is fully mounted and extract the measuring rope. Hook the rope clip on the measuring object and close the bracket of the clip. For your safety put a screw driver trough the clip to extract the rope.



- Check the track of the measuring target on collision with the sensor housing and on exceeding the specified measurement range. When installing the sensor make sure that the rubber stopper does not touch the rope outlet.
- Connect the electronics according to the sensor type. When laying the cables be careful not to under-run the minimal allowed bending radius of the cable (5 x cable diameter).
- The rope must be extracted from the sensor vertically. The maximum variation from the vertical is 3°. Avoid carefully extracting the rope at an inclination, since the durability of the instrument would shorten considerably. If it is not possible to keep the limit of 3°, a deflection pulley has to be used.
- The measuring range/ the zero point begins after approximately 2 mm extracted rope. The mechanical reserve at the end of the measuring range is about 20 mm.
- When mounting outdoors protect the sensor and the rope from ice-formation at temperatures below 0 °C.
- Lay the rope preferably in corners or guarded in guidings to prevent pollution or accidental touch.
- When operating the sensor, take care not to let the rope snap back by mistake or extract the rope over the specified measurement range, as this might destroy the sensor.
- Maintenance: These instruments are maintenance-free. If however, the rope is soiled due to adverse environmental conditions, it should be cleaned with a cloth drenched in resin-free machine oil.

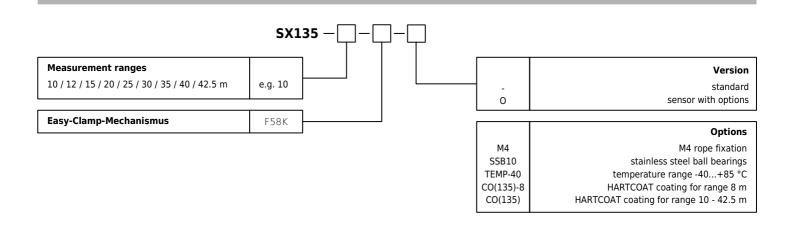
### ARNING NOTICES

- Don't let the rope snap back. If the rope is retracted freely, this may lead to injuries (whiplash effect) and the instrument may be damaged. Caution when unhooking and retracting the rope into the sensor.
- Never exceed the specified measurement range when extracting the rope!
- Don't try to open the instrument. The stored energy of the spring drive may lead to injuries when being mishandled.
- Don't touch the rope when operating the sensor.
- Avoid guiding the rope over edges or corners. Use a deflection pulley instead.
- Don't operate the sensor if the rope is buckled or damaged. A ripping of the rope may lead to injuries or damaging the sensor.

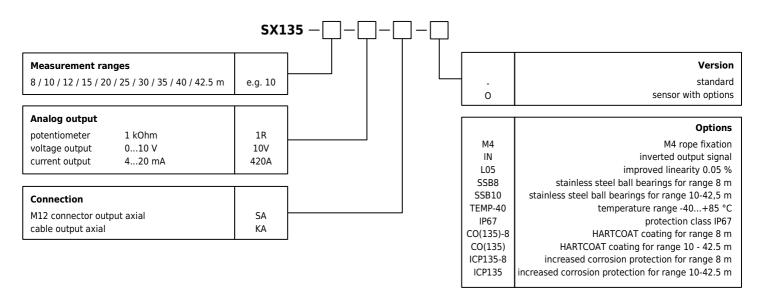


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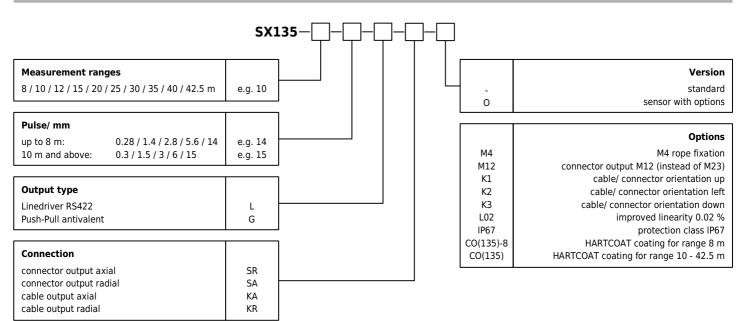
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## ORDER CODE ANALOG OUTPUT



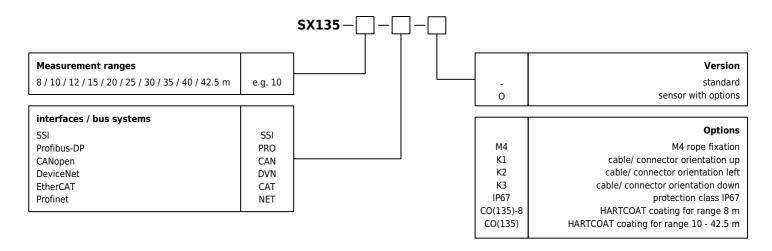
## ORDER CODE DIGITAL OUTPUT INCREMENTAL



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## ORDER CODE DIGITAL OUTPUT ABSOLUTE



## **OVERVIEW**

Base model draw wire mechanics (for encoder assembly)	Base model with potentiometer output
	SX135-8-1R
SX135-10-F58K	SX135-10-1R
SX135-12-F58K	SX135-12-1R
SX135-15-F58K	SX135-15-1R
SX135-20-F58K	SX135-20-1R
SX135-25-F58K	SX135-25-1R
SX135-30-F58K	SX135-30-1R
SX135-35-F58K	SX135-35-1R
SX135-40-F58K	SX135-40-1R
SX135-42,5-F58K	SX135-42,5-1R

With additional charge on -1R Version:		
Analog output		Digital output absolute
10V	Voltage output 010 V	SSI
420A	Current output 420 mA	CANopen
		Profibus-DP
Digital outp	ut incremental	DeviceNet
L/ G	Linedriver RS422/ Push-Pull	EtherCAT
		Profinet

Subject to change without prior notice.

Way Con Positions messtechnik

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