

Incremental Rotary Encoder

Large hollow shaft



measuring

monitoring

analysing



Max. speed: 6000 rpm

● Shaft: to Ø 42 mm

Output: RS422 or push-pull

Connector

Pulse count: 360-5000 pulsesMax. pulse frequency: 300 kHz

● Supply: 5/10-30 V_{DC}

Max. temperature: +75°C

Protection type: IP 65





Description

KOBOLD rotary encoders are used to measure length, position, rotational speed and angle. They convert mechanical motion to electrical signals. Incremental rotary encoders output a frequency signal which can represent speed, length or position.

A rotatable disc, on which a grating is attached, is mounted between an LED and a receiver. The light emitted from the LED is modulated by the grating and hits the receiver, which outputs a sinusoidal signal that is proportional to the light received. The sinusoidal signal is processed by specially designed electronics. Standard control systems - including all KOBOLD counters - require digital, square-wave signals at the input. Thus the signal is conditioned in the rotary encoder and is outputed through different output circuits depending on the field of application.

Areas of application:

- Mounting technology
- Feeders and handling machines for electrical components
- Test equipment
- Mechanical engineering

Technical Details

Max. speed: 1.500 rpm

Moment of inertia of rotor: approximately 150 x 10-6 kgm²

Initial torque: < 0.2 Nm Hollow shaft: Ø 42 mm or

Ø 25 mm stainless steel

Mechanical connection: flange

Impact resistance: 1000 m/s², 6 ms
Vibration resistance: 100 m/s², 10 - 2000 Hz

Operating

temperature range: -20 to +70 °C

Working

temperature range: -20 to +75 °C

Output circuit: push-pull without inversion

or RS422 with inversion (TTL-compatible) short-circuit-proof

Electrical connection: 12-pole plug connector, radial

Max. pulse frequency: 300 kHz

Supply: $10 - 30 V_{DC}$ (push-pull)

 $5 V_{DC} \pm 5\%$ (RS422)

Current consumption: 55 mA; max. 125 mA (push-pull)

40 mA; max. 90 mA (RS422)

Permissible load/channel: max. ± 30 mA (push-pull)

max. ± 20 mA (RS422)

Signal level high: min. U_B –3 V (push-pull)

min. 2.5 V (RS422)

Signal level low: max. 2.5 V (push-pull)

max. 0.5 V (RS422)

Rise time/fall time: max. 1 µs (push-pull)

max. 200 ns (RS 422)

Pulses per revolution: 360, 1000, 1024, 2048,

2500, 5000

Protection type: IP 65

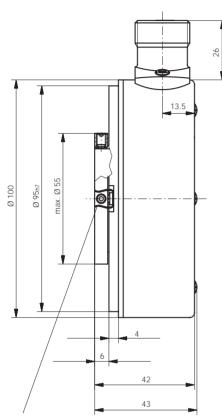
Weight: approximately 0.7 kg

Order details (Example: ZDI-CH 1B G 3 0200)

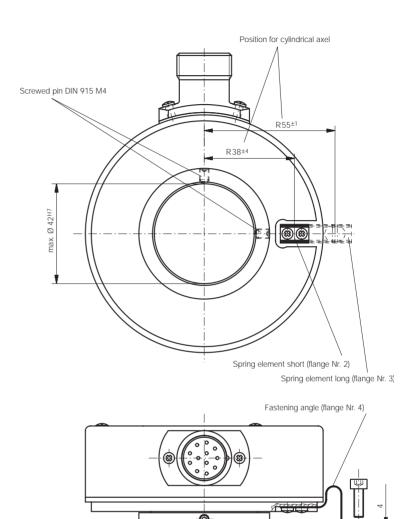
Model	Description	Hollow shaft	Output circuit	Electrical connection	Pulse count (always use 4 digits)
ZDI-CH	Incremental rotary encoder - shaft model	19 = Ø 25 mm 1B = Ø 42 mm	G= push-pull without inversion R= RS422 with inversion	3 =12-pole plug connector, radial	0360, 1000, 1024, 2048, 2500, 5000
ZDZ-G2	12-pole mating connector				



Dimensions



Spring element for cylindrical pen DIN 6325 \emptyset 6



Long hole for screw M4



Please refer to our brochure Z4...



...for time measurement